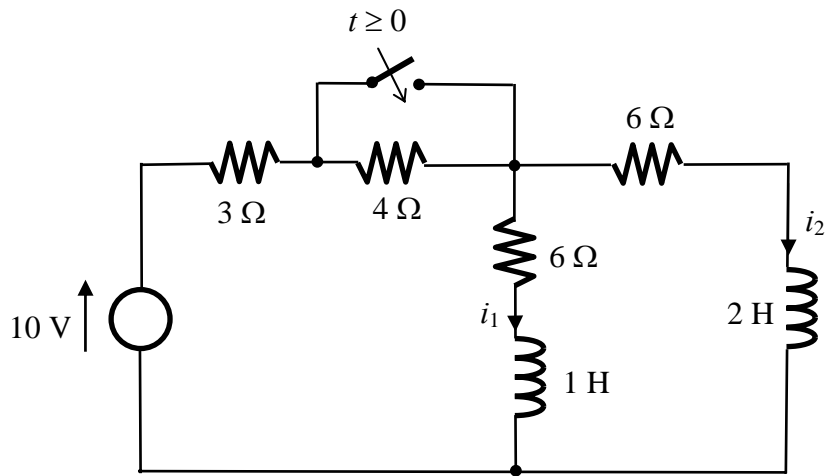
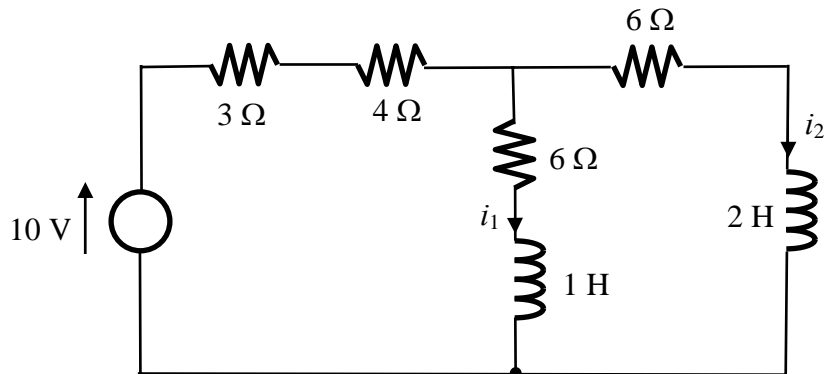


Q.1. In the electrical circuit given below, the switch has been in the position shown for a long time and is thrown to the other position for time $t \geq 0$.

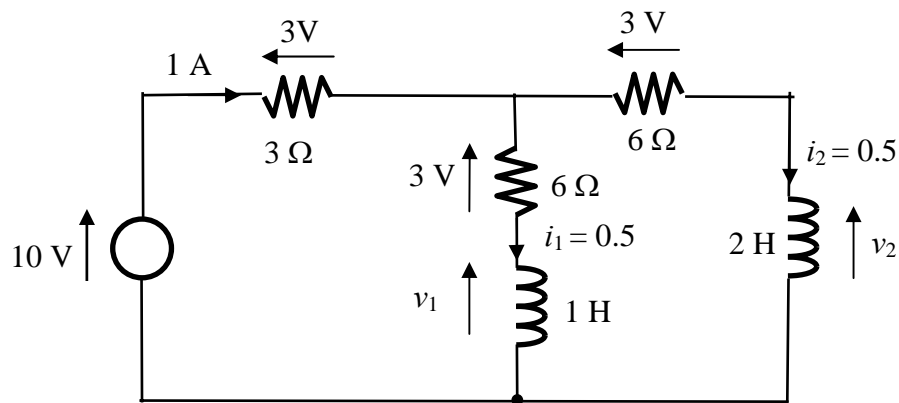


- (a) Determine the currents for both inductors for $t < 0$.
(4 marks)
- (b) Determine the currents and voltages for both inductors just right after the switch is closed.
(4 marks)
- (c) Derive the differential equation governing the circuit in terms of i_1 .
(10 marks)
- (d) Compute the roots of its characteristic polynomial.
(5 marks)
- (e) Is the circuit over damped, under damped or critically damped?
(2 marks)

Solution: (a) for $t < 0$, the inductors are of short-circuit. The total resistance connected to the voltage source is 10Ω and thus the current drawn from the source is 1 A , which will be equally distributed to the two parallel branches. Hence, $i_1 = i_2 = 0.5 \text{ A}$.

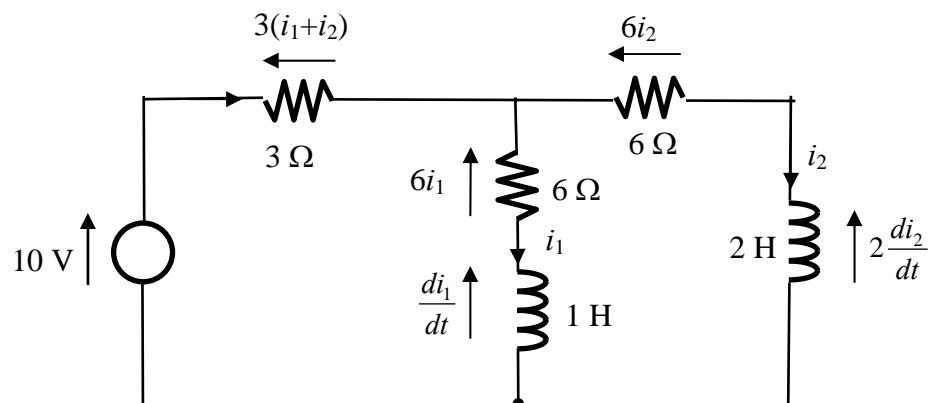


(b) Right after the switch is thrown to its final position, the inductor currents have to be continuous. Thus, $i_1 = i_2 = 0.5 \text{ A}$, which implies the current passing the 3Ω resistor is 1 A .



From the circuit above, it is clear that $v_1 = v_2 = 4 \text{ V}$.

(c) Refer to the figure below.



Applying KVL to the left loop, we obtain

$$\begin{aligned}\frac{di_1}{dt} + 6i_1 + 3(i_1 + i_2) = 10 &\Rightarrow \frac{di_1(t)}{dt} + 9i_1(t) + 3i_2(t) = 10 \Rightarrow 6i_2(t) = 20 - 2\frac{di_1(t)}{dt} - 18i_1(t) \\ &\Rightarrow \frac{d^2i_1(t)}{dt^2} + 9\frac{di_1(t)}{dt} + 3\frac{di_2(t)}{dt} = 0 \Rightarrow 2\frac{di_2(t)}{dt} = -\frac{2}{3}\frac{d^2i_1(t)}{dt^2} - 6\frac{di_1(t)}{dt}\end{aligned}$$

Applying KVL to the right loop, we obtain

$$\frac{di_1(t)}{dt} + 6i_1(t) = 2\frac{di_2(t)}{dt} + 6i_2(t) = -\frac{2}{3}\frac{d^2i_1(t)}{dt^2} - 6\frac{di_1(t)}{dt} + 20 - 2\frac{di_1(t)}{dt} - 18i_1(t)$$

Thus, we have

$$\frac{2}{3}\frac{d^2i_1(t)}{dt^2} + 9\frac{di_1(t)}{dt} + 24i_1(t) = 20$$

(d) The characteristic polynomial is given by

$$\frac{2}{3}z^2 + 9z + 24 = 0$$

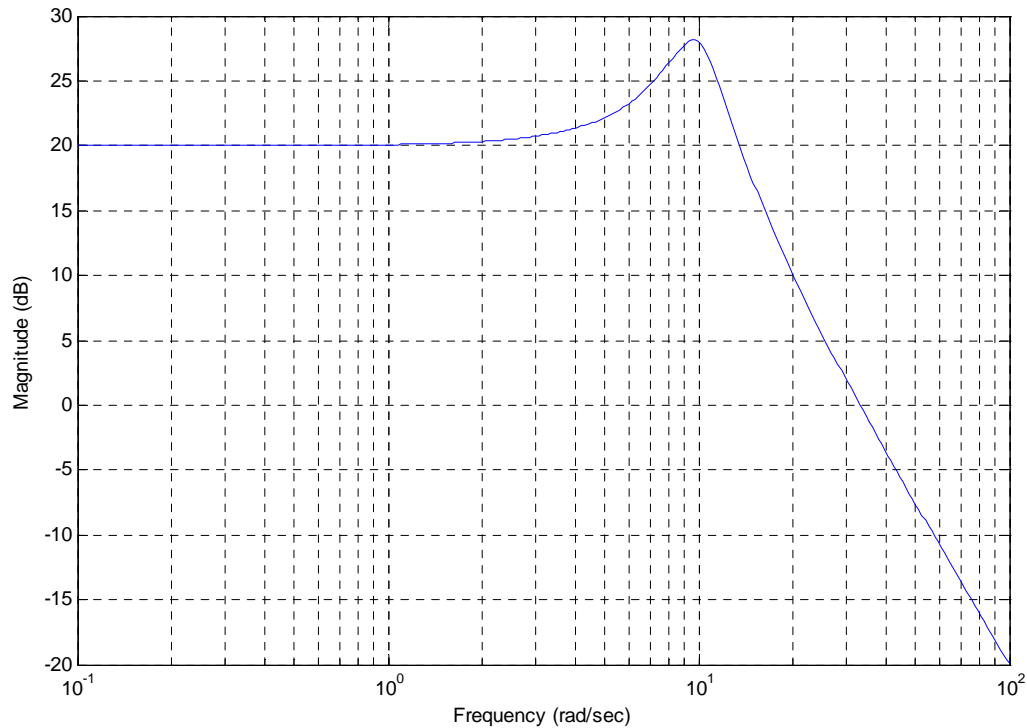
and its roots are $-9.8423, -3.6577$.

(e) The circuit is over damped as its characteristic polynomial has two distinct real roots.

Q.2. The magnitude response of a typical second order system characterized by

$$H(s) = \frac{Y(s)}{U(s)} = \frac{K\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

is given in Fig. 2 below.



- (a) Find the DC gain, K , the damping ratio, ζ , and the natural frequency, ω_n , of the given system.

(10 marks)

- (b) Given an input signal, $u(t) = \cos 10t$, find its corresponding steady-state output, $y(t)$.

(5 marks)

- (c) Find the overshoot, rise time, peak time and settling time of the unit step response of the system.

(5 marks)

- (d) Sketch the unit step response.

(5 marks)

Solution:

(a) It is simple to observe from the magnitude response that the DC gain is 20 dB, i.e.,

$$K = 10.$$

The corner frequency, which is also the natural frequency, of the magnitude response is about 10 rad/sec, i.e.,

$$\omega_n = 10 \text{ rad/sec.}$$

The peak at the corner frequency is about 28 dB with 20 dB being produced by the DC gain. Thus, the peak without the contribution from the DC gain is 8 dB, which is corresponding to a damping ratio $\zeta = 0.2$. Thus, the transfer function is given by

$$H(s) = \frac{Y(s)}{U(s)} = \frac{10^3}{s^2 + 4s + 10^2}$$

(b) For the given input, we have $\omega = 10$ rad/sec. Its corresponding frequency response is given by

$$H(j\omega)|_{\omega=10} = \frac{10^3}{(j10)^2 + j40 + 10^2} = \frac{25}{j} = 25 \angle -90^\circ$$

Thus, the corresponding steady-state output is given by

$$y(t) = 25 \cos(10 t - 90^\circ)$$

(c) Overshoot is given by $M_p = e^{-\pi\zeta/\sqrt{1-\zeta^2}} = e^{-3.14 \times 0.2/\sqrt{1-0.2^2}} = 0.53 = 53\%$

$$\text{Rise time } t_r = \frac{1.8}{\omega_n} = 0.18 \text{ sec}$$

$$\text{Peak time } t_p = \frac{\pi}{\omega_n \sqrt{1-\zeta^2}} = \frac{3.14}{10\sqrt{1-0.2^2}} = 0.32 \text{ sec}$$

$$\text{Settling time } t_s = \frac{4}{\zeta\omega_n} = 2 \text{ sec}$$

(d) Step response...

